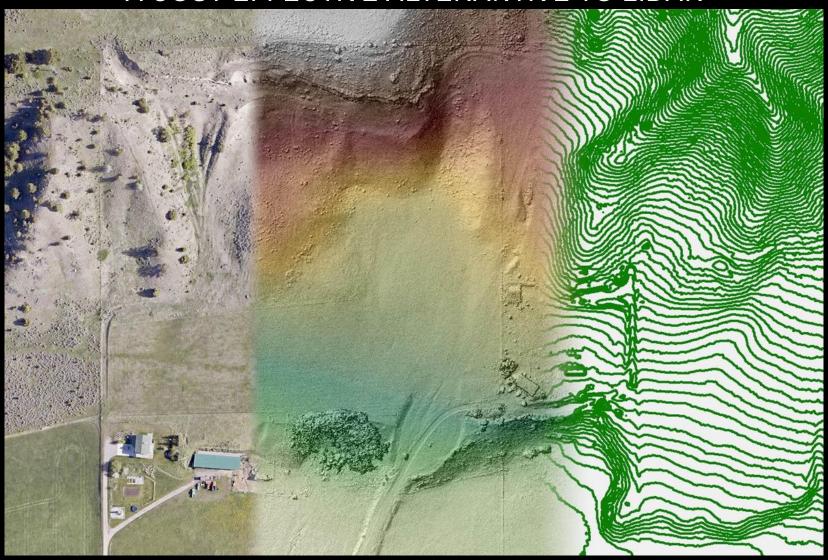
STRUCTURE FROM MOTION (SfM) 3D LANDSCAPE MAPPING AND MODELING: A COST-EFFECTIVE ALTERANTIVE TO LIDAR



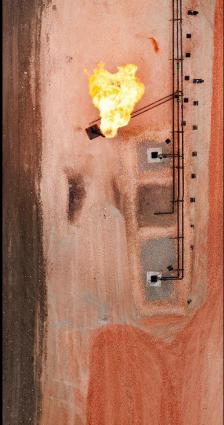
ASSOCIATION OF MONTANA FLOODPLAIN MANAGERS 17th ANNUAL CONFERENCE CHRIS BOYER CALEB LUCY

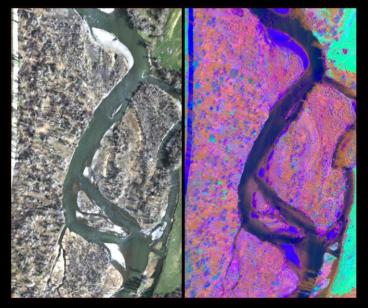












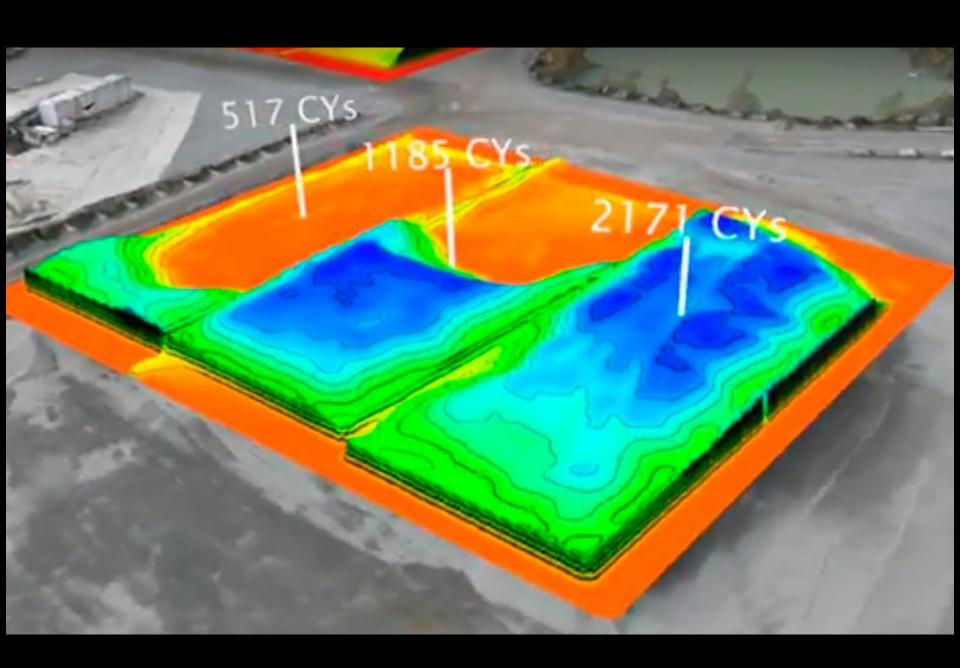






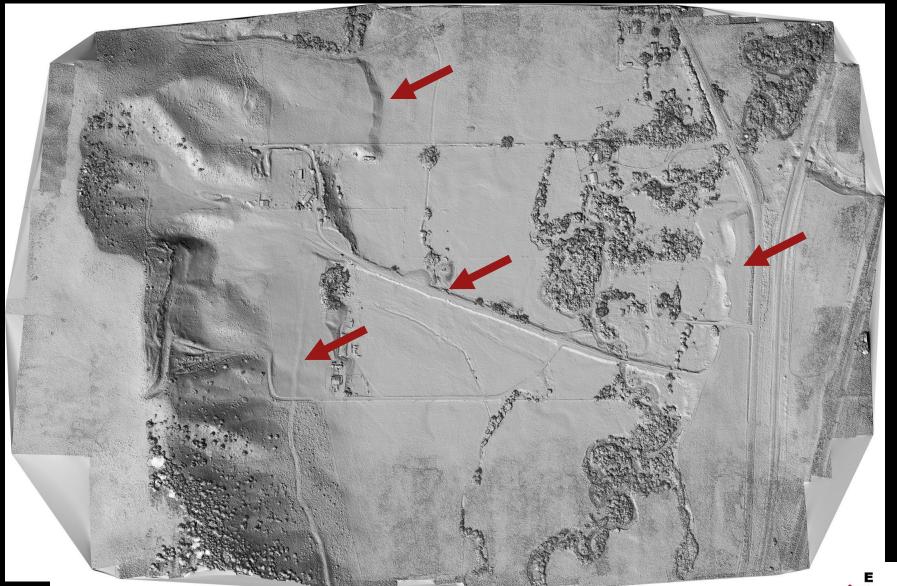






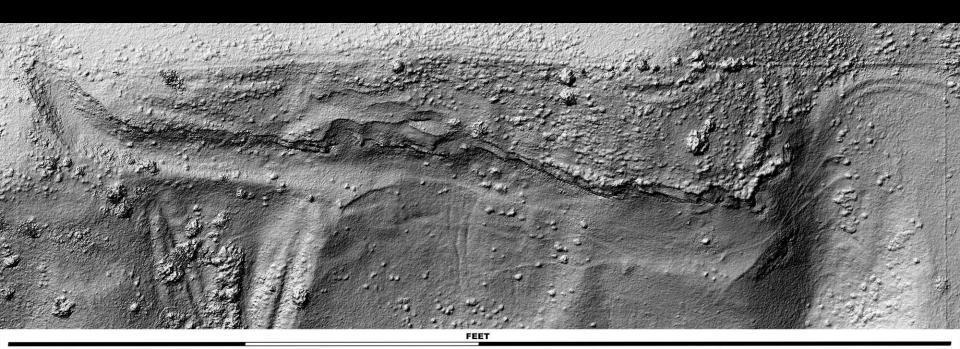








N S





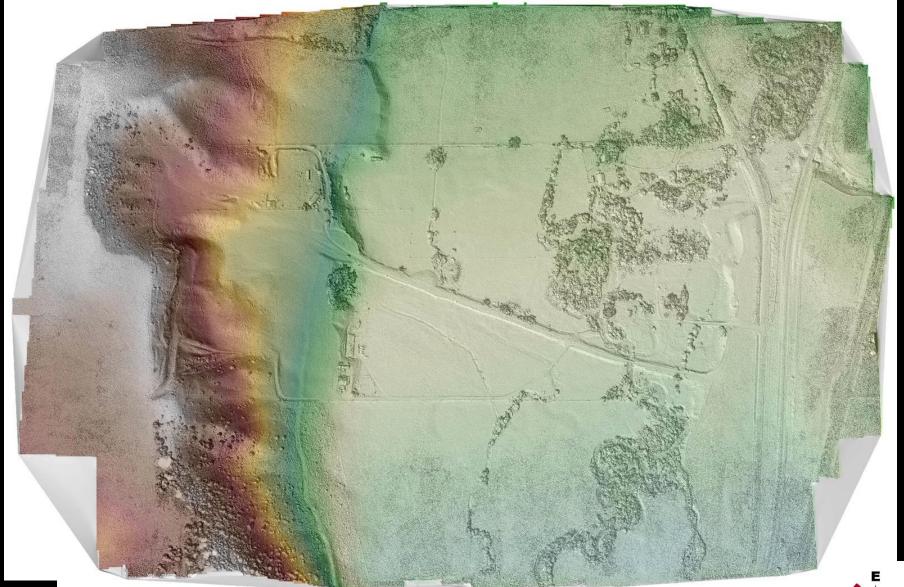




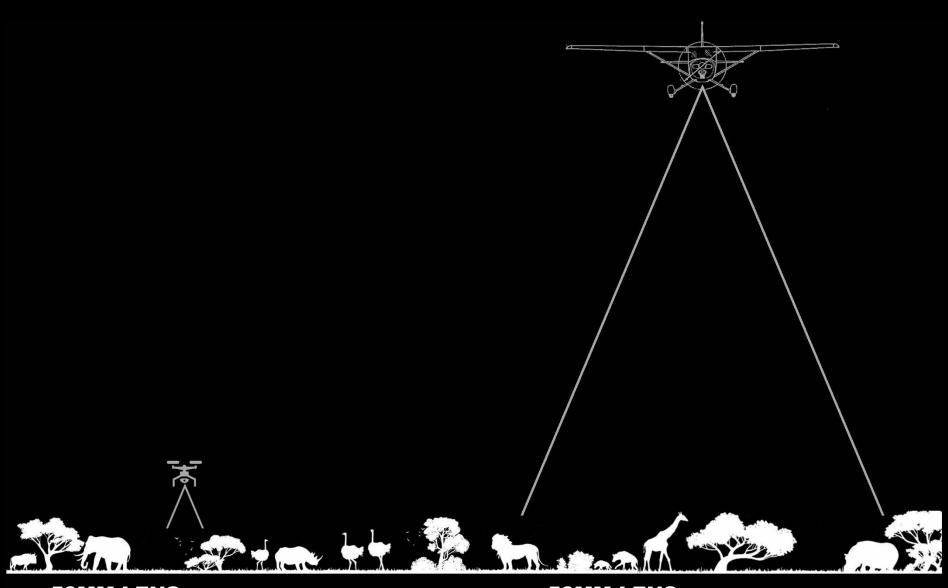


Image USDA Farm Service Agency

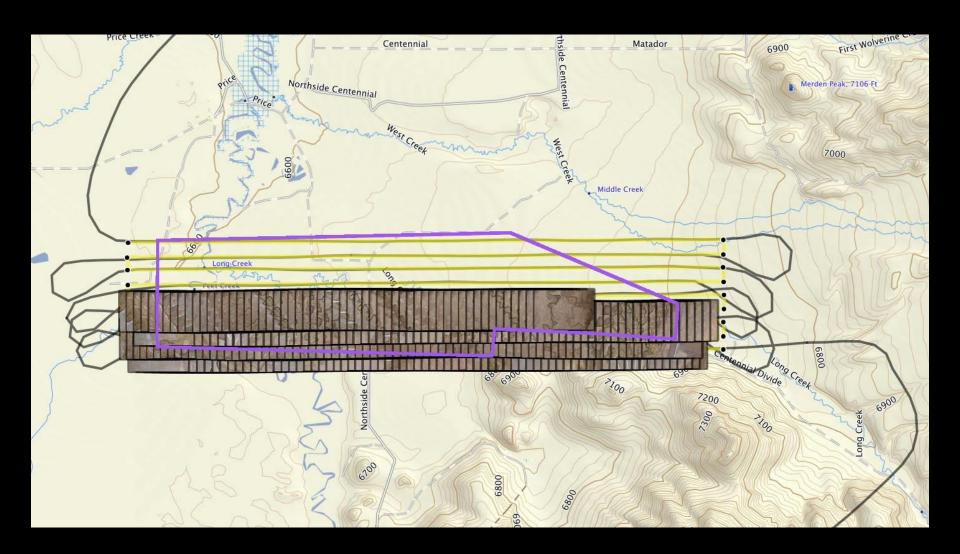
Google earth

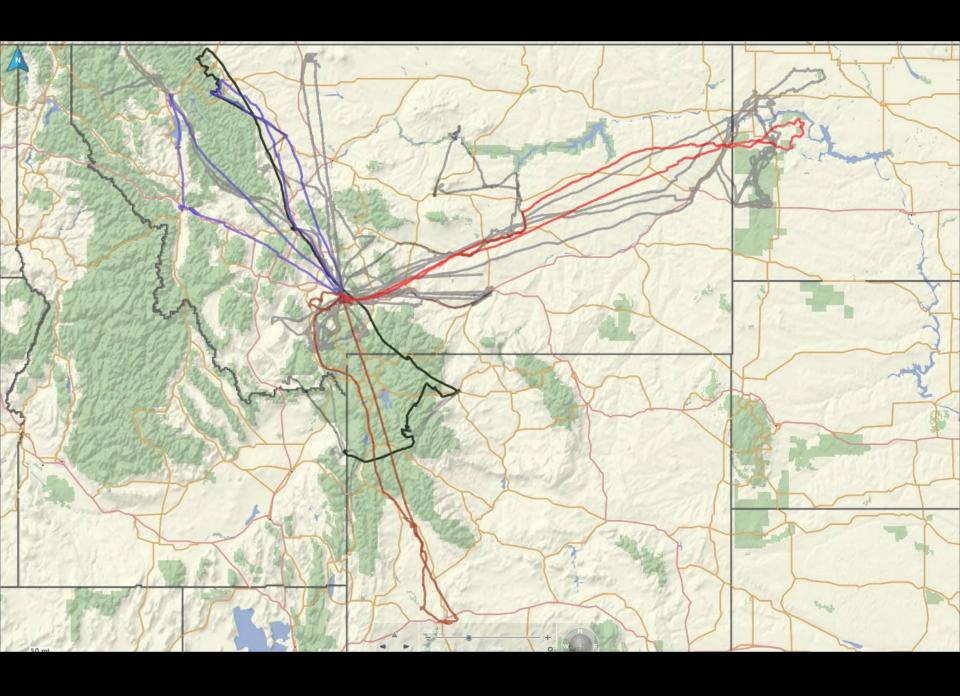






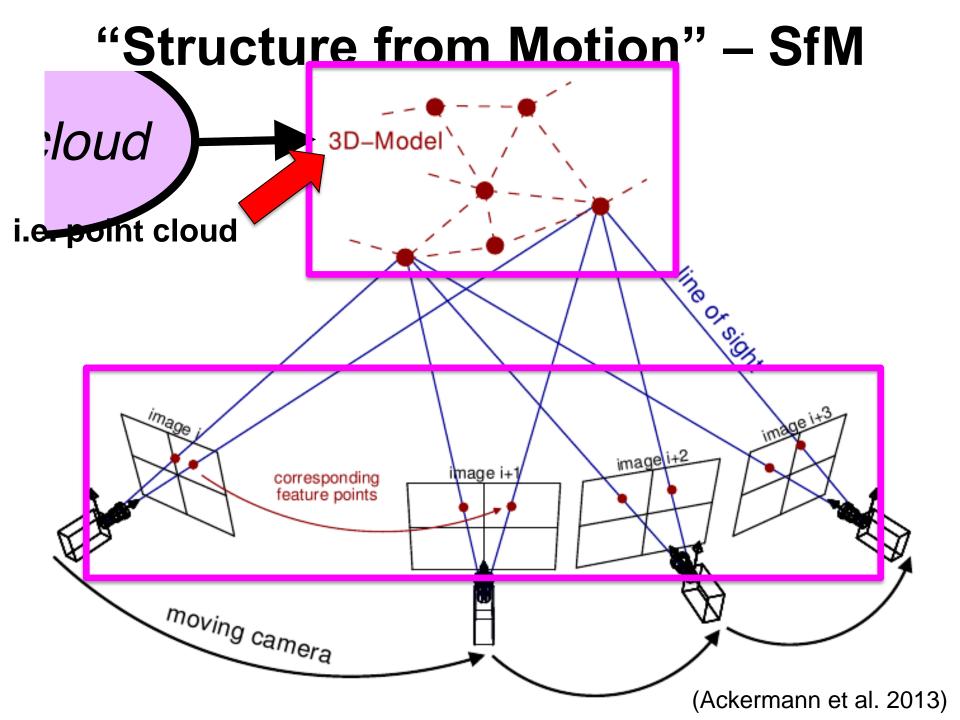
50MM LENS 400' AGL 288' x 192' COVERAGE 1.25 ACRES 50MM LENS 2,500' AGL 1,800' x 1,200' COVERAGE 50 ACRES







ASSOCIATION OF MONTANA FLOODPLAIN MANAGERS 17th ANNUAL CONFERENCE CHRIS BOYER CALEB LUCY



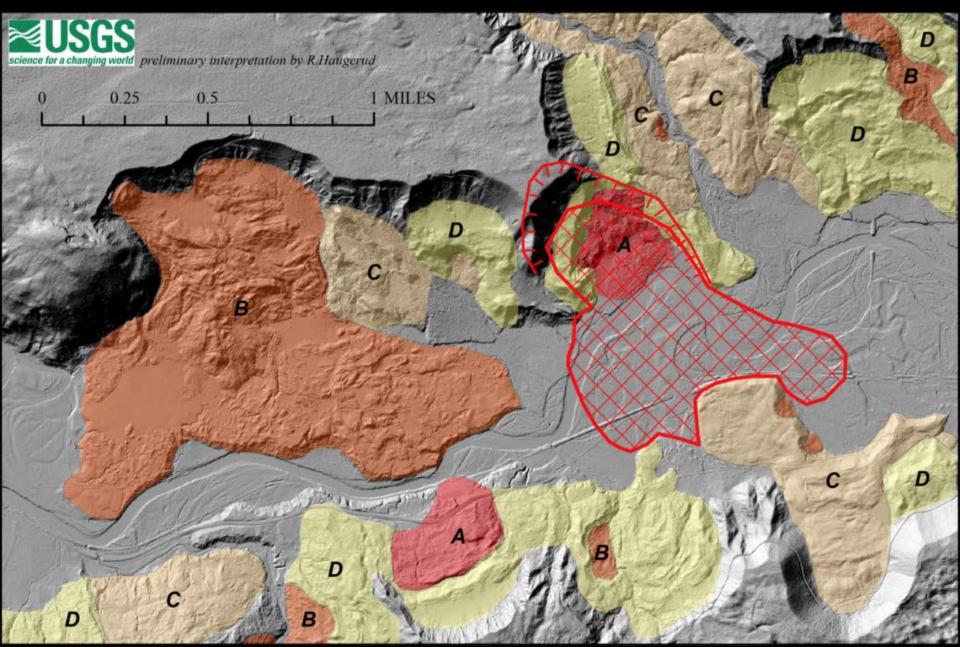


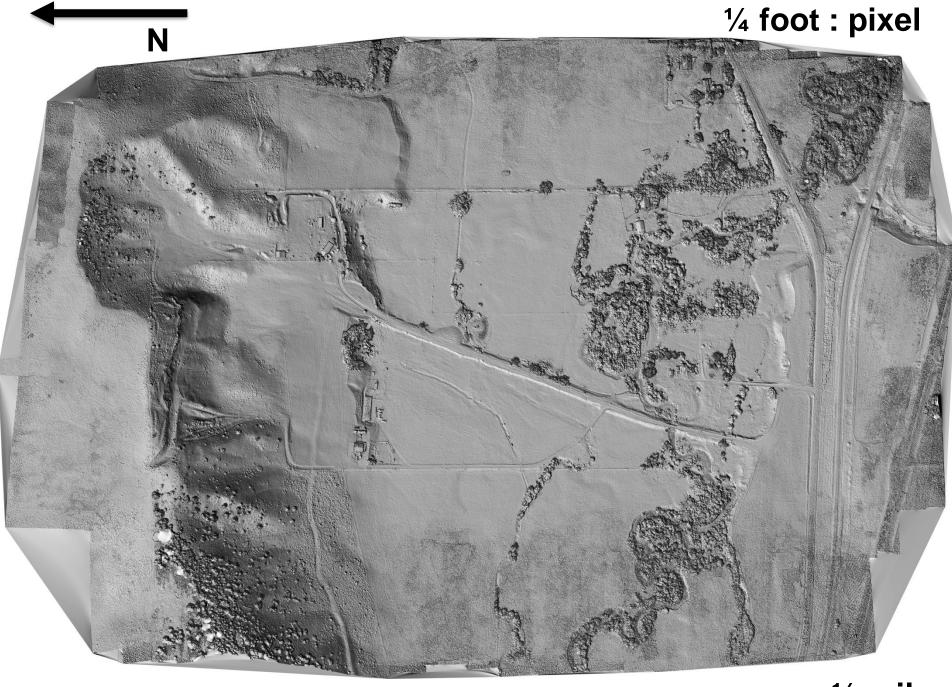
3/22/2014: Landslide in Oso, WA

"How to Make Landslides Less Deadly" by David R. Montgomery and Joseph Wartman NYT 3/20/2015

Over the past decade, the science of landslide mapping has advanced rapidly, largely because of improvements in remote sensing technologies that allow us to see Earth's surface in unprecedented detail. Today, it would be possible to create high-resolution hazard maps for the entire nation for significantly less than the estimated \$1 billion or more in losses that landslides cause each year in the United States.

These high-resolution maps are available in other countries, including New Zealand, Italy and Switzerland, where they provide valuable information to citizens and public officials about risks. They guide land-use policy and allow people to make informed decisions before buying or building a home.



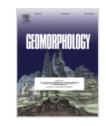


1/4 mile



Geomorphology

Volume 200, 15 October 2013, Pages 172–183



The Field Tradition in Geomorphology 43rd Annual Binghamton
Geomorphology Symposium, held 21-23 September 2012 in Jackson,
Wyoming USA

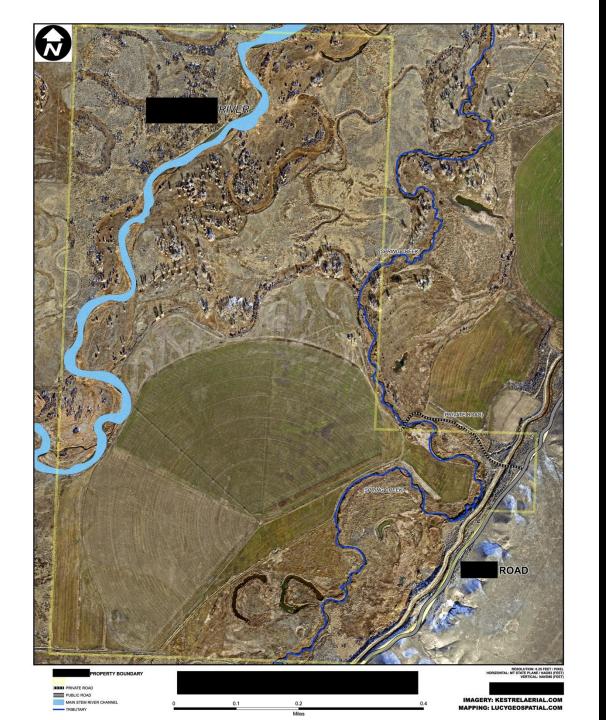
'You are HERE': Connecting the dots with airborne lidar for geomorphic fieldwork

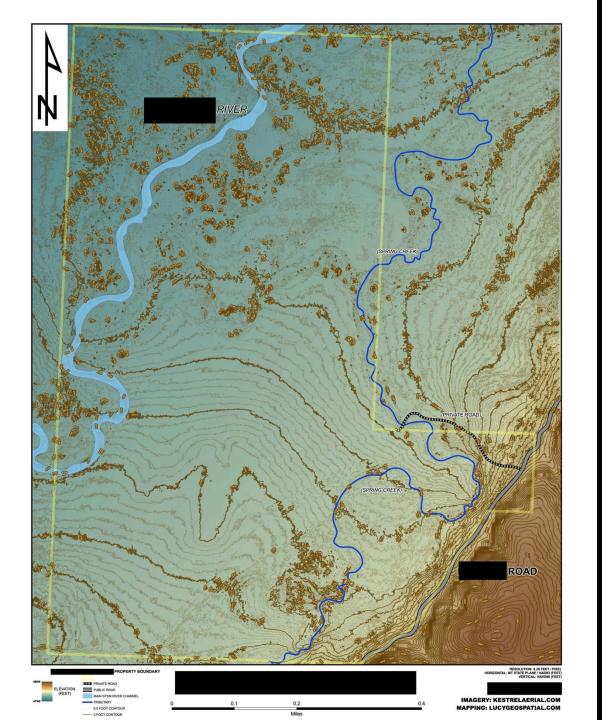
Joshua J. Roering ♣ , ➡, Benjamin H. Mackey¹, Jill A. Marshall, Kristin E. Sweeney, Natalia I. Deligne², Adam M. Booth³, Alexander L. Handwerger, Corina Cerovski-Darriau

B Show more

Lidar (and high-resolution landscape imagery in general) affords:

- 1) Best basemap, esp. for guiding field studies*
- 2) More information to evaluate, more robust results
- 3) Perspective to identify previously unknown landscape features





"Point Clouds: Lidar versus 3D Vision"

from F. Leberl et al (2010) Photogrammetric Engineering & Remote Sensing

TABLE 3. SIXTEEN ADVANTAGES OF THE PHOTOGRAMMETRIC 3D WORKFLOW OVER THE DIRECTLY MEASURED LASER POINT CLOUDS

Accuracy and Errors

- 1. Large area rigid camera image block geometry via AT at a sub-pixel accuracy
- 2. Error checking using redundant observations as a system-inherent verification
- 3. Internal accuracy measures from redundancy
- 4. Geometric accuracy by AT superior to a reliance on GPS/IMU to fuse patches into seamless coverage
- 5. Greater point density → for better defined discontinuities

Economy

- 6. Superior data collection efficiency with faster vehicles, larger swaths
- 7. Single workflow within aerial application, all image-based
- 8. Single workflow across widely varying applications (aerial, street-side & indoor)
- 9. No occlusions using no-cost along-track high image overlaps

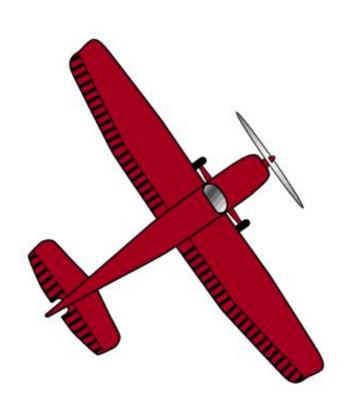
Data Types

- 10. 2D-image information augmenting 3D data points
- 11. Multi-spectral image classification
- 12. Urban façade textures available at no cost from the air at image edges
- 13. Images document details \rightarrow example street signs can be read automatically

Miscellaneous

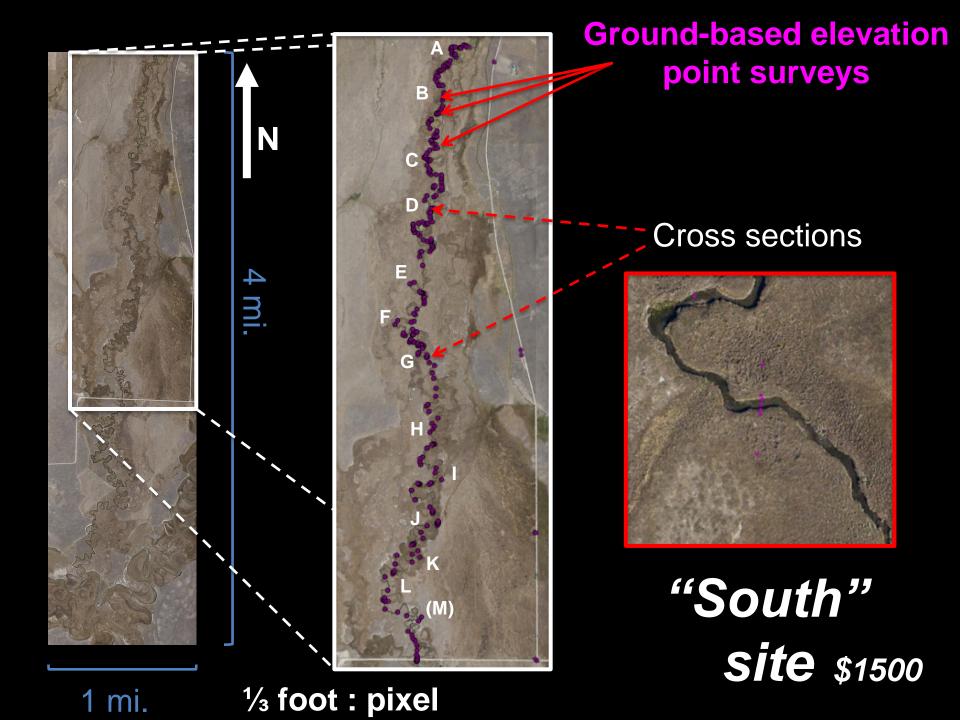
- 14. Perspective exists towards Real time 3DVision via "supercomputer in match box"
- 15. Full automation needs image redundancy → lidar adds little to automation
- 16. Scene interpretation is becoming important and needs imagery → lidar adds little

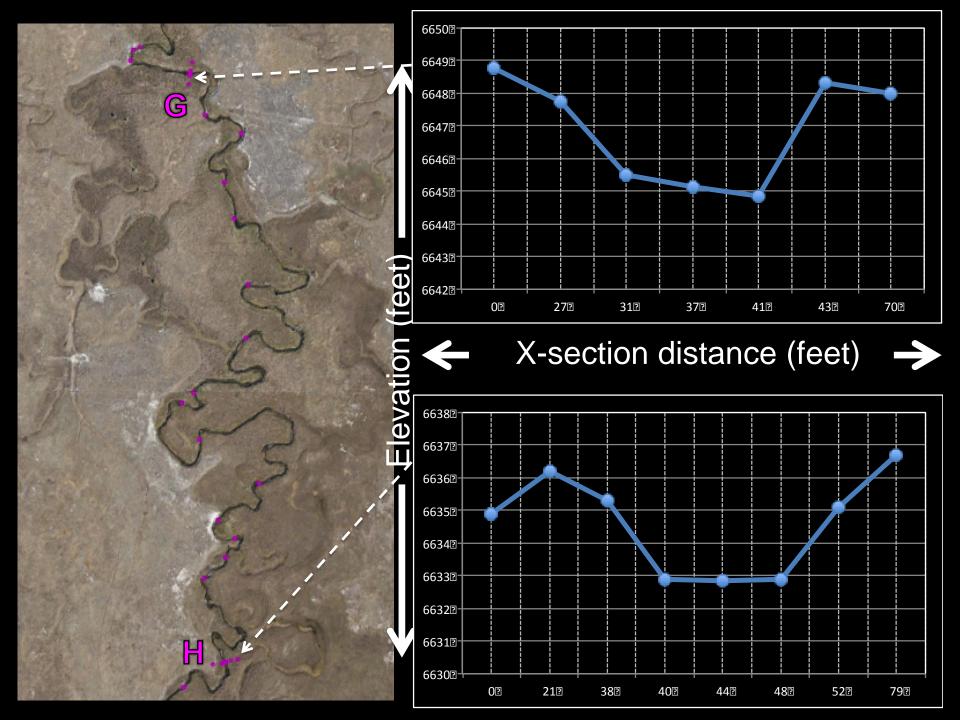
Objective

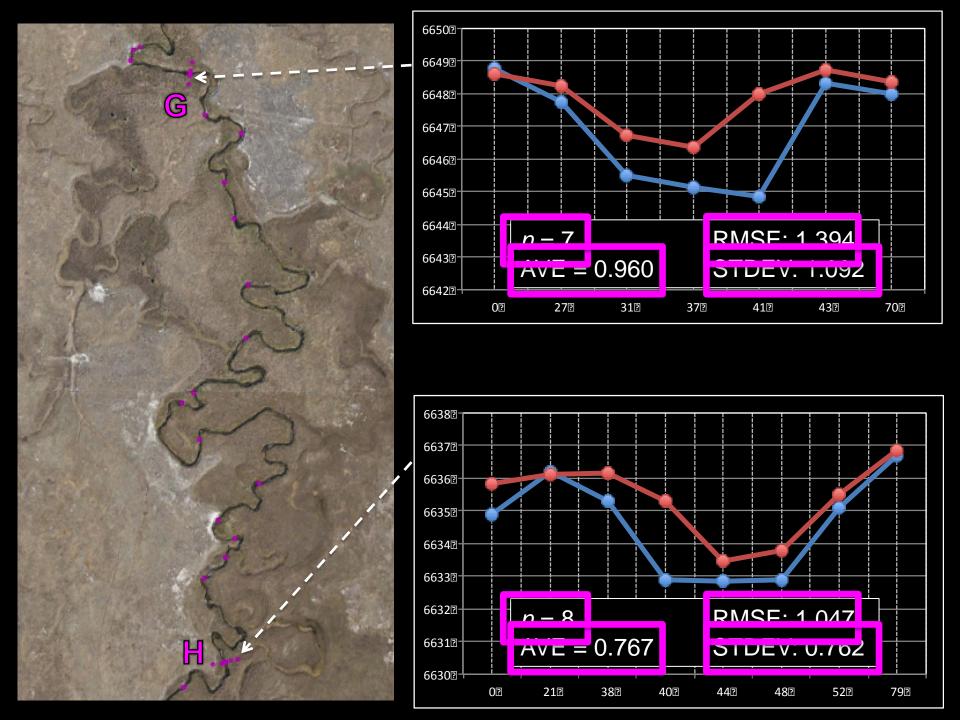


V.









"SOUTH" SITE-WIDE z(SfM)-z(LS) RESULTS SUMMARY

```
0.718 ft ±1.689 (1.833 RMSE; n = 565) — raw
0.378 ft ±1.563 (1.606 RMSE; n = 341) — subaerial
1.236 ft ±1.743 (2.133 RMSE; n = 224) — subaqueous
```

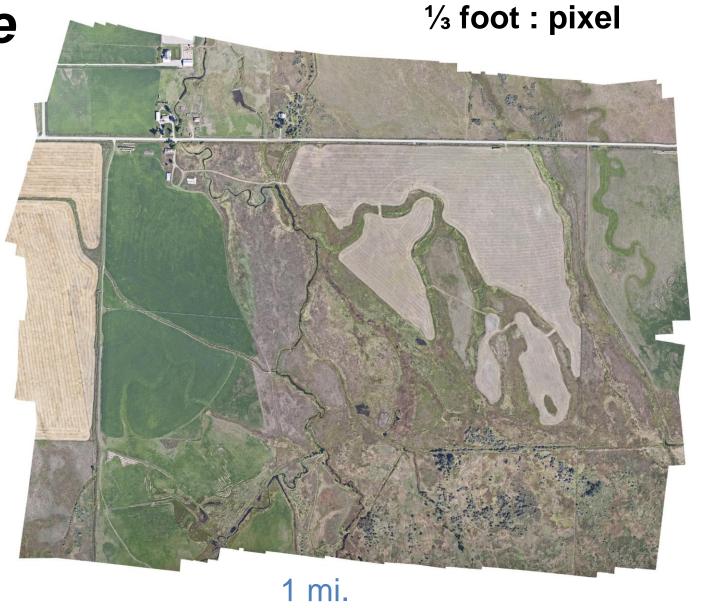
(13) cross sections: 0.813 ft ±1.359 (1.578 RMSE; n = 104)

"North"

site

\$250





"NORTH" SITE-WIDE z(SfM)-z(LS) RESULTS SUMMARY

```
0.007 ft \pm 1.700 (3.213 RMSE; n = 691) — raw
```

-0.077 ft ±1.730 (3.158 RMSE; n = 616) — subaerial

0.693 ft ±1.250 (3.631 RMSE; n = 75) — subaqueous

(29) cross sections: -0.225 ft ±1.464 (1.476 RMSE; n = 301)

Conclusions / Future work

- Further model testing

- Image classification

- Repeat surveys

???

ACKNOWLEDGEMENTS

Chris Boyer Scott Gillian @ Gaia Resources Noah Snyder @ Boston College